## In the Claims:

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Claims 1 to 15 (Canceled).

- (Currently amended) Method for milling a freeform surface 16. on a workpiece using a milling machine, whereby the workpiece is milled by a tool of the milling machine [[in]] such a manner so that a desired freeform surface is formed, and to carry out the milling the tool is moved relative to the workpiece along a tool path defined by splines whereby the motion of the tool is controlled based on the splines, characterized in that the splines are calculated directly from support points stored in workpiece coordinates or in machine coordinates in a CAD/CAM system, and, independent of the freeform surface to be formed, and the tool path is generated from six splines if the support points are defined in workpiece coordinates, and is generated from five splines if the support points are defined in machine coordinates, whereby one independent spline is produced for each coordinate.
- 17. (Previously presented) Method according to claim 16,
  2 characterized in that, for each tool path, the splines are
  3 calculated through the use of one or more interpolation
  4 parameters which are equal for all of the splines of the
  5 respective tool path, so that all of the splines of the
  6 respective tool path are synchronized with one another.

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18. (Currently amended) Apparatus for milling a freeform surface on a workpiece, whereby a tool is adapted to mill the workpiece in such a manner so that a desired freeform surface is formed, comprising a programming arrangement (21) for programming a tool path, and comprising at least one control arrangement (28) for controlling a motion of the tool relative to the workpiece along the tool path defined by splines, characterized in that the programming arrangement (21) is embodied as a CAD/CAM system, and further comprising means (25) allocated to the programming arrangement (21) and adapted to calculate the splines directly from support points stored in workpiece coordinates or machine coordinates in the CAD/CAM system in such a manner so that the means (25), independent of the freeform surface to be formed, are adapted to generate the tool path from six splines if the support points are defined in workpiece coordinates, and from five splines if the support points are defined in machine coordinates, independent spline is produced for coordinate, and wherein the CAD/CAM system is adapted to produce at least one APT file (22), and further comprising least one downstream-connected post-processor (26) adapted to convert the at least one APT file into at least one control file (27) that is executable by the or each control arrangement (28), and whereby the or each control arrangement (28) is adapted to control the motion of the tool along the tool path based on and in accordance with the splines.

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- (Previously presented) Apparatus according to claim 18, 19. further comprising an APT processor (23), characterized in that the means (25) allocated the programming to arrangement (21) are arranged and adapted to transfer the splines to the APT processor (23) which is arranged and adapted transfer to the splines to the or each post-processor (26), whereby the or each post-processor (26) is arranged and adapted to provide the splines to the or each control arrangement (28) in a polynomial format.
- 20. (Currently amended) A method of milling a freeform surface on a workpiece using a miller tool, comprising the steps:
  - a) defining tool path way points, each respectively in six workpiece coordinates or five machine coordinates, wherein said way points define points within tolerance limits along a contour of a nominal freeform surface that is to be milled;
  - on and fitting said way points sufficiently closely to remain within said tolerance limits of said contour, wherein a respective independent one of said splines is respectively generated for each one of said workpiece coordinates or said machine coordinates of all of said way points, so that said plurality of splines includes a total of six splines respectively allocated to said six workpiece coordinates if said way points are defined in said six workpiece

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coordinates, and said plurality of splines includes a total of five splines respectively allocated to said five machine coordinates if said way points are defined in said five machine coordinates; and

to said workpiece so that said miller tool mills said workpiece, and controlling said moving of said miller tool based on and in accordance with said plurality of splines respectively allocated to said workpiece coordinates or said machine coordinates so that said miller tool moves along a tool path defined by said splines in said workpiece coordinates or said machine coordinates and thereby mills an actual freeform surface on said workpiece within said tolerance limits of said contour of said nominal freeform surface.

21. (Currently amended) An apparatus for milling a freeform surface on a workpiece, comprising:

a movable miller tool that is movable relative to the workpiece;

plural control arrangements respectively adapted to control a motion of said miller tool respectively in six workpiece coordinates or in five machine coordinates;

a programming arrangement programed programmed to define tool path way points in said six workpiece coordinates or in said five machine coordinates, wherein said way points define points within tolerance limits along

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a contour of a nominal freeform surface that is to be milled;

> a processing arrangement that is interposed between said programming arrangement and said control arrangements, and that is adapted and programmed to generate a plurality of splines directly dependent on and fitting said way points sufficiently closely to remain within said tolerance limits of said contour, wherein a respective independent one of said splines is respectively to be generated for each one of said workpiece coordinates or said machine coordinates of all of said way points, so that said plurality of splines includes a total of six splines respectively allocated to said six workpiece coordinates if said way points are defined in said six workpiece coordinates, and said plurality of splines includes a total of five splines respectively allocated to said five machine coordinates if said way points are defined in said five machine coordinates; and

> wherein said control arrangements are adapted to control the motion of said miller tool <u>based on and</u> in accordance with said plurality of splines respectively allocated to said workpiece coordinates or said machine coordinates so that said miller tool is adapted to move along a tool path defined by said splines in said workpiece coordinates or said machine coordinates and thereby to mill an actual freeform surface on said workpiece within said tolerance limits of said contour of said nominal freeform surface.